LIDAR INFRASTRUCTURE TRAFFIC MONITORING

A QUIET DIGITAL MAP OF THE WORLD

Just as modern vehicles are becoming smarter and more autonomous, we explore how to make infrastructure more intelligent. This white paper provides insights on automated safety based on LiDAR infrastructure monitoring to ensure the safety for all road users.

Authors: Boson, Erik; Käck, Andreas; Rehnström, Ida



Flasheye develops leading perception software for 3D sensors, making your systems understand what 3D sensors are seeing. The vision is to unlock the potential of high-capacity sensors in any environment, making them accessible and installable by anyone. Flasheye started in the mining industry and is now growing in new sectors and beyond.



QRTECH is one of the few independent design and development houses in the Nordics within electronics and software. We function as an agile and powerful complement and support to established R&D departments, and as an enabler for fastgrowing companies and scale-ups. QRTECH is a wholly owned subsidiary within the Embron Group.

flasheye.se

grtech.se

Executive Summary

The LiDAR (Light Detection and Ranging) technology is essential for autonomous vehicles and robots, offering a high-resolution digital representation of the physical environment using laser pulses. This spatial awareness is crucial for safe navigation in real-world environments. To achieve traffic-safe autonomous operation, smart infrastructure is a vital complement to sensors mounted on the vehicle itself. Fixed LiDAR sensors in the infrastructure can provide comprehensive environmental data to both human drivers and autonomous vehicles, enhancing overall safety.

LiDAR in the infrastructure VS. LiDAR on the vehicles

- Smart infrastructure is feasible, cost-effective, and powerful, particularly when all activities and traffic occur in confined areas, such as industrial zones.
- Instead of each vehicle being responsible for its own safety, fixed LiDAR sensors in the infrastructure can provide both human drivers and autonomous vehicles with comprehensive environmental information, which individual vehicles may lack [4].

The goal to reduce human errors

The human factor is responsible for approximately 95% of accidents. Urban areas account for 38% of failures, while only 7% occur on highways. Interestingly, only about 16% of errors are related to cloudy weather, and just 1% occur during rainy or snowy conditions. Most disengagements (82%) happen in good weather, demonstrating that most errors are not linked to bad weather conditions [28]. To achieve Vision Zero, the human factor must be addressed.



Increased interest in ITS

Intelligent Traffic Systems market growth is projected to reach USD 27.56 Billion by 2030, with an annual growth rate of 12.3% [26], driven by safety and automation. Even modern vehicles equipped with driver assistance systems, designed to reduce accidents and optimize driving, would benefit from external environmental data. LiDAR is widely used in automotive and robotics for collision avoidance and perception, e.g. detecting objects hundreds of meters away, enabling vehicles to stop at high speeds.

Outstanding and reliable 3D data

By utilizing information from the infrastructure, we can accurately track surrounding vehicles' positions in real-time, allowing prediction of potential risks. This information plays a crucial role in the development of autonomous systems that can respond more quickly and precisely to changes in traffic dynamics [6], [22].



Addressing the challenges in ITS

The total understanding of the surroundings is missing

Signalized intersections, commonly used to manage traffic, often become hotspots for incidents due to ground sensors for vehicles and activation buttons for pedestrians that control light signals [3]. These intersections lack the intelligence to fully understand all situations, leading to accidents [4], [18], [25]. LiDAR technology and perception software can address this with reliable real-time monitoring of everything that moves in the scene to prevent incidents and enhance traffic flow [3], [4], [18], [22], [24]. With real-time awareness, drivers can be alerted or traffic lights controlled more intelligently than today's systems or provide the existing system with new information [3], [18], [24]. Additionally, LiDAR in the infrastructure provides a bird's-eye view of the scene, which vehicle sensors cannot.

Real-life scenarios are complex, and conditions are various

A smart system must handle challenges like extreme weather (rain, snow, fog), urban issues (shadows, reflections, potholes, poor lighting), and unique situations (exhaust emissions, smooth surface reflections, and open vehicle doors). Cameras struggle with poor lighting, especially at night, making them unsuitable for real-time data [14], [25]. A comparison of video and LiDAR shows that while LiDAR performs similarly during the day, it outperforms video in low-light conditions, such as late evening [25], and strong sunlight, which is a known problem for cameras.

Overview of existing technologies

LiDAR technology is not expensive and out of reach anymore

While technologies like cameras and radar lack the precision of LiDAR [8], [17], [25], LiDAR has traditionally been too expensive for widespread use in driver assistance systems. However, as LiDAR prices decrease with growing popularity, it is now becoming feasible to install in traffic systems [17], [24], [18]. This enables the shift to smart cities, where vehicles can connect to infrastructure for safer traffic and LiDAR monitoring can provide traditional systems, such as traffic lights, with situational awareness [3], [4], [17].

Video and radar provide limited information and lack reliability

Cameras, now popular for their cost-effectiveness, provide detailed analysis and advanced object classification in favorable conditions [25], [28]. However, they struggle with visibility issues and 3D scene representation, making them less effective in real-time safety-critical systems. Using two cameras to create a 3D point cloud can address this, but real-time 3D object detection remains challenging. Radar, effective for medium to long-range mapping and poor weather conditions, detects objects up to 150 meters, far surpassing the 10-meter range of human drivers in similar conditions. However, radar lacks the fine resolution needed for precise object identification, making it less suitable for detailed scene analysis [28]. While video and radar are complementary, LiDAR provides both spatial perception and precision for understanding surroundings and classifying objects.

Both cameras and radar have limited fields of view, leading to blind spots, a problem LiDAR in the infrastructure avoids with its wide-area, high-quality data [7], [14], [25]. Offering 360-degree, high-resolution mapping across short and long ranges, LiDAR excels in low-visibility and poor lighting conditions, making it the standard sensor for many advanced systems [7]. Active sensing, such as RADAR, LiDAR, and ultrasound, emits signals and detects reflections, allowing control over frequency and direction in various conditions. In contrast, passive sensing, like cameras, captures environmental signals without emitting energy [28].

Capabilities needed for a smart traffic monitoring system

Purpose	Capabilities
High reliability under various conditions	 Not sensitive to light and weather conditions
	Real-time and minimal latency
Cost effective	Easy implementation
	Optimized field of view
	Coverage of large areas
High accruacy and precision	Spatial perception of the environment
	High visibility
	 Detailed and accurate information about each object

Intelligent traffic lights

Traffic light control is a basic ITS application that optimizes traffic flow and improves safety by reducing jams, lowering driver stress, and protecting vulnerable road users (VRUs).

Key hazards involve timing transitions and preventing conflicting green lights.

ITS systems for traffic light control can be implemented straightforwardly by ensuring safety requirements at lower levels and adding higher-level ITS functions without compromising safety. A LiDAR-based system offers the advantage of anonymized data for GDPR compliance, allowing data reuse [28].



Take the next step towards autonomous excellence

In conclusion, researchers provide a detailed overview of the main challenges related to obstacle detection and safety for automated and autonomous vehicles, and they agree that most of these problems can be addressed by using LiDAR monitoring in the infrastructure. Additionally, implementing LiDAR-based ITS can make a big difference in the less complex scenarios already today, e.g. by providing information and insights to traffic lights, to improve traffic flow and safety, this without being connected to vehicles. LiDAR data represents outstanding and highly valuable data streams. With perception software, your systems can utilize auto-labeled data to enhance the overall performance without the need of annotation or training the system. The information can also be used for immediate actions like closing a road from vulnerable road users or to alert drivers and pedestrians. By integrating AI, this system not only provides real-time awareness but also optimizes operations over time, enhancing understanding of trends and patterns.

References

This White Paper is based on a pre-study about automated traffic safety, funded by FFI Sweden 2024.

- 1. Afandizadeh, S., & Hamid, B. R. (2023). Investigation of Traffic Accidents Prediction Models and Effective Human Factors: A review. www.jcema.com. https://doi.org/10.22034/jcema.2023.187705
- 2. Andrew, J., (2024, accessed 2024-11-04), Peachtree Corners uses LiDAR to increase road safety, https://cities-today.com/peachtreecorners-uses-lidar-to-increase-road-safety/
- 3. Ansariyar, A. (2023), Evaluating sensor accuracy at signalized intersections: A comparative study of LiDAR and CCTV technologies. SSRN Electronic Journal. https://doi.org/10.2139/ssrn.4600716
- 4.Arnold, E., Dianati, M., De Temple, R., & Fallah, S. (2020). Cooperative perception for 3D object detection in driving scenarios using infrastructure sensors. IEEE Transactions on Intelligent Transportation Systems, 23(3), 1852–1864. https://doi.org/10.1109/tits.2020.3028424
- 5. Bucsuházy, K., Matuchová, E., Zůvala, R., Moravcová, P., Kostíková, M., & Mikulec, R. (2020). Human factors contributing to the road traffic accident occurrence. Transportation Research Procedia, 45, 555–561. https://doi.org/10.1016/j.trpro.2020.03.057
- 6.Cheng, C., Gao, Y., Min, H., & Zhao, X. (2020). An accurate autonomous vehicles positioning method based on GPS/LIDAR/Camera in V2V communication environment. CICTP 2021, 495–507. https://doi.org/10.1061/9780784482933.043
- 7. Cui, G., Zhang, W., Xiao, Y., Yao, L., & Fang, Z. (2022). Cooperative Perception Technology of Autonomous Driving in the Internet of Vehicles Environment: a review. Sensors, 22(15), 5535. https://doi.org/10.3390/s22155535
- 8. Creß, C., Bing, Z., & Knoll, A. C. (2023). Intelligent Transportation Systems Using Roadside Infrastructure: A literature survey. IEEE Transactions on Intelligent Transportation Systems, 25(7), 6309–6327. https://doi.org/10.1109/tits.2023.3343434
- 9. European Commission (2024). Road safety thematic report Main factors causing fatal crashes. European Road Safety Observatory. Brussels, European Commission, Directorate General for Transport.
- 10. Federal Highway Administration, Driver Adaptation to Vehicle Automation: The Effect of Driver Assistance Systems on Driving Performance and System Monitoring (Washington, DC: 2022) https://doi.org/10.21949/1521875.
- Fukatsu, R., & Sakaguchi, K. (2021). Automated Driving with Cooperative Perception Using Millimeter-wave V2I Communications for Safe and Efficient Passing Through Intersections. IEEE, 1–5. https://doi.org/10.1109/vtc2021-spring51267.2021.9449017
- 12. Goodall, N. J. (2014). Machine Ethics and automated vehicles. In Lecture notes in mobility (pp. 93–102).https://doi.org/10.1007/978-3-319-05990-7_9
- Greenblatt, J. B., & Shaheen, S. (2015). Automated vehicles, On-Demand mobility, and environmental impacts. Current Sustainable/Renewable Energy Reports, 2(3), 74–81. https://doi.org/10.1007/s40518-015-0038-5
- 14. Gupta, A., Jain, S., Choudhary, P., & Parida, M. (2024). Dynamic object detection using sparse LiDAR data for autonomous machine driving and road safety applications. Expert Systems With Applications, 255, 124636. https://doi.org/10.1016/j.eswa.2024.124636
- 15.Intertraffic (2024, accessed 2024-11-04), How LIDAR Tech can facilite safer, smarter transportation, https://www.intertraffic.com/news/lidar-safe-smart-transportation
- 16.Blincoe, L., Miller, T.R., Wang, J-S., Swedler, D., Coughlin, T., Lawrence, B., Guo, F., Klauer, S., and Dingus, T. (2022). "The economic and societal impact of motor vehicle crashes, 2019," NHTSA: Washington, DC, USA, Tech. Rep., 2022.
- 17.Lv, B., Xu, H., Wu, J., Tian, Y., Zhang, Y., Zheng, Y., Yuan, C., & Tian, S. (2019). LIDAR-Enhanced connected infrastructures sensing and broadcasting High-Resolution traffic information serving smart cities. IEEE Access, 7, 79895–79907. https://doi.org/10.1109/access.2019.2923421
- 18.Mo, Y., Vijay, R., Rufus, R., De Boer, N., Kim, J., & Yu, M. (2024). Enhanced perception for autonomous vehicles at obstructed intersections: an implementation of vehicle to infrastructure (V2I) collaboration. Sensors, 24(3), 936. https://doi.org/10.3390/s24030936
- 19.Mål 3: God hälsa och välbefinnande Globala målen. (2024, September 13). Globala Målen. https://www.globalamalen.se/om-globalamalen/mal-3-halsa-och-valbefinnande/
- 20.0thman, K. (2021). Public acceptance and perception of autonomous vehicles: a comprehensive review. Al And Ethics, 1(3), 355–387. https://doi.org/10.1007/s43681-021-00041-8
- 21. Pradhan, A. K., Pai, G., Jeong, H., & Bao, S. (2022). Simulator evaluation of an intersection maneuver assist system with connected and automated vehicle technologies. Ergonomics, 66(7), 999–1014. https://doi.org/10.1080/00140139.2022.2121006
- 22.Shan, M., Narula, K., Wong, Y. F., Worrall, S., Khan, M., Alexander, P., & Nebot, E. (2020). Demonstrations of cooperative perception: Safety and robustness in connected and automated vehicle operations. Sensors, 21(1),200. https://doi.org/10.3390/s21010200
- 23.Shetty, A., Yu, M., Kurzhanskiy, A., Grembek, O., Tavafoghi, H., & Varaiya, P. (2021). Safety challenges for autonomous vehicles in the absence of connectivity. Transportation Research Part C Emerging Technologies,128, 103133. https://doi.org/10.1016/j.trc.2021.103133
- 24.Srinivasan, A., Mahartayasa, Y., Jammula, V. C., Lu, D., Como, S., Wishart, J., Yang, Y., & Yu, H. (2022). Infrastructure-Based LiDAR monitoring for assessing automated driving safety. SAE Technical Papers on CD-ROM/SAE Technical Paper Series. https://doi.org/10.4271/2022-01-0081
- 25. Wu, A., Banerjee, T., Chen, K., Rangarajan, A., & Ranka, S. (2023). A Multi-Sensor Video/LiDAR system for analyzing intersection safety. Conference Paper. https://doi.org/10.1109/itsc57777.2023.10422349
- 26. Research, S. (n.d.). Intelligent Traffic Systems Market. https://straitsresearch.com/report/intelligent-traffic-systems-market
- 27. Yasar, A., Adnan, M., Ectors, W., & Wets, G. (2023). Comparison review on LIDAR technologies vs. RADAR technologies in speed enforcement system. Personal and Ubiquitous Computing, 27(5), 1691–1700.https://doi.org/10.1007/s00779-023-01736-x
- 28. Yu, X., & Marinov, M. (2020). A Study on Recent Developments and Issues with Obstacle Detection Systems for Automated Vehicles.

🚸 Flasheye

Flasheye develops leading perception software for 3D sensors, making your systems understand what 3D sensors are seeing. The vision is to unlock the potential of high-capacity sensors in any environment, making them accessible and installable by anyone. Flasheye started in the mining industry and is now growing in new sectors and beyond.



QRTECH is a leading company in the development of electronics, software, and digital services with its origin from world-leading automotive industry's research. They operate in high-tech industries and contribute in the development of autonomous solutions. They guide, assist, and develop solutions so that customers can maximize the benefits of growing digital technology.

flasheye.se